

**ADVANCED PLACEMENT PHYSICS B EQUATIONS DEVELOPED FOR 2012**

NEWTONIAN MECHANICS		ELECTRICITY AND MAGNETISM	
$v = v_0 + at$	$a =$ acceleration	$F = \frac{kq_1q_2}{r^2}$	$A =$ area
$x = x_0 + v_0t + \frac{1}{2}at^2$	$F =$ force	$\mathbf{E} = \frac{\mathbf{F}}{q}$	$B =$ magnetic field
$v^2 = v_0^2 + 2a(x - x_0)$	$f =$ frequency	$U_E = qV = \frac{kq_1q_2}{r}$	$C =$ capacitance
$\Sigma \mathbf{F} = \mathbf{F}_{net} = m\mathbf{a}$	$h =$ height	$E_{avg} = -\frac{V}{d}$	$d =$ distance
$F_{fric} \leq \mu N$	$J =$ impulse	$V = k\left(\frac{q_1}{r_1} + \frac{q_2}{r_2} + \frac{q_3}{r_3} + \dots\right)$	$E =$ electric field
$a_c = \frac{v^2}{r}$	$K =$ kinetic energy	$C = \frac{Q}{V}$	$\mathcal{E} =$ emf
$\tau = rF \sin \theta$	$k =$ spring constant	$C = \frac{\epsilon_0 A}{d}$	$F =$ force
$\mathbf{p} = m\mathbf{v}$	$\ell =$ length	$U_c = \frac{1}{2}QV = \frac{1}{2}CV^2$	$I =$ current
$\mathbf{J} = \mathbf{F}\Delta t = \Delta \mathbf{p}$	$m =$ mass	$I_{avg} = \frac{\Delta Q}{\Delta t}$	$\ell =$ length
$K = \frac{1}{2}mv^2$	$N =$ normal force	$R = \frac{\rho \ell}{A}$	$P =$ power
$\Delta U_g = mgh$	$P =$ power	$V = IR$	$Q =$ charge
$W = F\Delta r \cos \theta$	$p =$ momentum	$P = IV$	$q =$ point charge
$P_{avg} = \frac{W}{\Delta t}$	$r =$ radius or distance	$C_p = C_1 + C_2 + C_3 + \dots$	$R =$ resistance
$P = Fv \cos \theta$	$T =$ period	$\frac{1}{C_s} = \frac{1}{C_1} + \frac{1}{C_2} + \frac{1}{C_3} + \dots$	$r =$ distance
$\mathbf{F}_s = -k\mathbf{x}$	$t =$ time	$R_s = R_1 + R_2 + R_3 + \dots$	$t =$ time
$U_s = \frac{1}{2}kx^2$	$U =$ potential energy	$\frac{1}{R_p} = \frac{1}{R_1} + \frac{1}{R_2} + \frac{1}{R_3} + \dots$	$U =$ potential (stored) energy
$T_s = 2\pi\sqrt{\frac{m}{k}}$	$v =$ velocity or speed	$F_B = qvB \sin \theta$	$V =$ electric potential or potential difference
$T_p = 2\pi\sqrt{\frac{\ell}{g}}$	$W =$ work done on a system	$F_B = BI\ell \sin \theta$	$v =$ velocity or speed
$T = \frac{1}{f}$	$x =$ position	$B = \frac{\mu_0 I}{2\pi r}$	$\rho =$ resistivity
$F_G = -\frac{Gm_1m_2}{r^2}$	$\mu =$ coefficient of friction	$\phi_m = BA \cos \theta$	$\theta =$ angle
$U_G = -\frac{Gm_1m_2}{r}$	$\theta =$ angle	$\mathcal{E}_{avg} = -\frac{\Delta \phi_m}{\Delta t}$	$\phi_m =$ magnetic flux
	$\tau =$ torque	$\mathcal{E} = B\ell v$	